In the Claims:

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- 1 1. (original) Tri-axial monolithic acceleration sensor (1),
 which comprises the following characteristic features:
 - a) the acceleration sensor (1) consists of plural individual sensors (2a-d) with respectively a main sensitivity axis (11) arranged on a common substrate (8),
 - b) each individual sensor (2a-d) is rotatably movably suspended on two torsion spring elements (4a-h) and comprises a seismic mass (3a-d) with a center of gravity (S_a , S_b , S_c and S_d),
 - c) each individual sensor (2a-d) comprises means for the measurement (10) of the deflection of the seismic mass (3a-d),

characterized in that

- d) the acceleration sensor (1) consists of at least three identical individual sensors (2a-d),
- e) each individual sensor (2a-d) is suspended eccentrically relative to its center of gravity (S_a , S_b , S_c , S_d) and
- 20 f) is rotated relative to the other individual sensors
 21 (2a-d) by 90°, 180° or 270°.
- 2. (original) Acceleration sensor according to claim 1, characterized in that the at least three identical individual sensors (2a-d) are arranged in a rectangle.

Claims 3 to 7 (canceled).

- 1 8. (new) Acceleration sensor according to claim 1,
 2 characterized in that the substrate (8) is arranged between
 3 a lower cover disk (7) and an upper cover disk (9) for the
 4 sealing and for the protection against environmental
 5 influences.
- 1 9. (new) Acceleration sensor according to claim 1,
 2 characterized in that a measurement of the deflection of
 3 each seismic mass (3a-d) is achieved by means of a
 4 differential capacitive measurement.
- 10. (new) Acceleration 1 sensor according to claim 9, characterized in that metallized surfaces (10a-d) that are 2 isolated from one another are structured on the upper cover 3 (9) close to the torsion axis defined by 5 respective torsion spring element (4a-h) for the differential capacitive measurement.
- 1 11. (new) Acceleration sensor according to claim 10,
 2 characterized in that the surfaces (10a-d) are arranged
 3 symmetrically to the torsion axis defined by the respective
 4 torsion spring element (4a-h).
- 1 12. (new) Bi-axial monolithic acceleration sensor (1), that
 2 comprises the following characteristic features:

- the acceleration sensor (1) consists of two individual sensors (2a-d) with respectively a main sensitivity axis (11) arranged on a common substrate (8),
 - b) each individual sensor (2a-d) is rotatably movably suspended on two torsion spring elements (4a-h) and comprises a seismic mass (3a-d) with a center of gravity (S_a , S_b , S_c and S_d),
 - c) each individual sensor (2a-d) comprises means for the measurement (10) of the deflection of the seismic mass (3a-d),

characterized in that

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- d) the acceleration sensor (1) consists of two identical individual sensors (2a-d),
- e) each individual sensor (2a-d) is suspended eccentrically relative to its center of gravity (S_a , S_b , S_c , S_d) and is rotated by 180° relative to the other individual sensor (2a-d) and
- f) the main sensitivity axis (11) of the one individual sensor (2a-d) extends vertically to the substrate (8) and the main sensitivity axis (11) of the other individual sensor (2a-d) extends vertically to the substrate (8).
- 1 13. (new) Acceleration sensor according to claim 12,
 2 characterized in that the substrate (8) is arranged between
 3 a lower cover disk (7) and an upper cover disk (9) for the
 4 sealing and for the protection against environmental
 5 influences.

- 1 14. (new) Acceleration sensor according to claim 12,
 2 characterized in that a measurement of the deflection of
 3 each seismic mass (3a-d) is achieved by means of a
 4 differential capacitive measurement.
- 1 **15**. (new) Acceleration sensor according to claim 14, 2 characterized in that metallized surfaces (10a-d) that are 3 isolated from one another are structured on the upper cover disk (9) close to the torsion axis defined by respective torsion spring element (4a-h) for the differential capacitive measurement.
- 1 16. (new) Acceleration sensor according to claim 15, 2 characterized in that the surfaces (10a-d) are arranged 3 symmetrically to the torsion axis defined by the respective 4 torsion spring element (4a-h).

[AMENDMENT CONTINUES ON NEXT PAGE]